Nico Schiavone

nschiavo@ualberta.ca \(\rightarrow \text{mesophil.github.io} \(\rightarrow \text{linkedin.com/in/nicoschiavone} \(\rightarrow \text{github.com/mesophil} \)

EDUCATION

University of Toronto, Department of Computer Science

Sept 2024 - May 2026

M.Sc. Computer Science

Toronto, ON

Vector Institute Affiliate; Supervisor: Dr. Sheila McIlraith

University of Alberta, Department of Electrical & Computer Eng.

Sept 2019 - May 2024

B.Sc. Engineering Physics with a Mathematics Minor

Edmonton, AB

3.95/4.00 Cumulative GPA, First Class Standing

Languages/Tools: Python, Java, MATLAB, Julia, JavaScript, Git, Playwright, GCP

Awards: NSERC Undergraduate Research Award x 3, Dean's Research Award, Most Outstanding ECE Research Award.

Interests: Calligraphy, fountain pens, futsal, life drawing, writing, math competitions.

EXPERIENCE

University of Alberta

Jan 2023 – June 2024

Machine Learning Researcher | Python, PyTorch

Edmonton, AB (Remote)

- Designed an efficient **computer vision** algorithm in Python, utilizing a novel sample selection algorithm that rivals state-of-the-art models while also using 80% less annotation data, resulting in a **first author** conference paper, selected for **oral presentation** and published at IEEE CAI 2024. (<u>GitHub</u>)
- Engineered algorithms using **reinforcement learning** and **large pretrained models** for data efficient classification based on adaptive image synthesis, resulting in another **first author** manuscript. (<u>GitHub</u>)

TELUS Jan 2023 – Aug 2023

Software Engineer Co-op | Python, Java, C++, SQL, GCP

Toronto, ON (Remote)

- Spearheaded the development of a **full stack** XML scripting tool for a 20+ person team to automatically correct errors between sets of files, reducing the time spent per file by 95%.
- Developed a **full stack** document extraction tool, increasing pipeline efficiency by 90+% for teams of 10+ people.
- Prototyped a revenue prediction planning tool with GCP, reducing time spent on data analysis by 75%.

TRIUMF May 2022 – Aug 2022

Software Research & Development Co-op | C++, Python

Vancouver, BC

- Independently operated and maintained an entire DAQ gantry and laser test facility for the Hyper-K group.
- Designed a Raspberry-Pi based safety and monitoring system in Python for a sensitive test facility of 15+ people.
- Contributed high quality code to the existing TRIUMF codebase, used by 50+ researchers nationwide.

PROJECTS

Huginn - Autonomous Retrieval Drone (<u>GitHub</u>): Self-guided custom drone using computer vision for object detection, real-time classification, and a novel magnetic interface for object pickup. Made in Python using PyTorch, Mavlink, and ROS.

UniScraper (GitHub): Web scraping tool using Scrapy and Playwright in Python for the ecommerce site Uniqlo, which allows for easy filtering of the entire site to find desirable items.

PUBLICATIONS

N. Schiavone, X. Li (2024). Reinforcement Learning with Generative Models for Compact Support Sets (link)

N. Schiavone, J. Wang, S. Li, R. Zemp, X. Li (2024). *MyriadAL: Active Few Shot Learning for Histopathology*. [IEEE CAI 2024, Oral Presentation (Top ~15% of accepted papers)] (link)